9 Interoperability aspects of fuzzy sets

Fuzzy Systems Engineering Toward Human-Centric Computing

Contents

9.1. Fuzzy sets and its family of α -cuts

9.2. Fuzzy sets and their interfacing with the external world

- 9.33. Encoding and decoding as an optimization problem of vector quantization
- 9.4. Decoding of a fuzzy set through a family of fuzzy sets
- 9.5. Taxonomy of data in structure description with shadowed sets

9.1 Fuzzy sets and its family of α -cuts

From fuzzy set to a family of sets

 Representation theorem offers an important insight into links between a given fuzzy set and its α-cuts

• Any fuzzy set can be represented as an infinite family of α -cuts

$$A = \bigcup_{\alpha > 0} \alpha A_{\alpha}$$

 $A_{\alpha} = \{ x \in \mathbf{X} \mid A(x) \ge \alpha \}$

Reconstruction







Reconstruction





From fuzzy set to a family of sets: An optimization

• Is there an optimal level a that optimizes a single α -cut of A so that A_a approximates A to the highest extent?

Performance index

$$Q = \int_{x \notin A_{\alpha}} A(x) dx + \int_{x \in A_{\alpha}} (1 - A(x)) dx$$

 $\min_{\alpha} Q = Q(\alpha_{opt})$

$$\alpha_{opt} = \arg \min_{\alpha} Q(\alpha)$$

Triangular fuzzy sets optimization

$$A(x) = \max(1 - \frac{x}{b}, 0), \ x \ge 0$$

$$Q = \int_{b(1-\alpha)}^{b} \left(1 - \frac{x}{b}\right) dx + \int_{0}^{b(1-\alpha)} \left(1 - 1 - \frac{x}{b}\right) dx$$

$$Q = b - b(1 - \alpha) + b(1 - \alpha)^2 - \frac{b}{2}$$

$$\frac{\partial Q}{\partial \alpha} = 0 \quad \Rightarrow \quad \alpha = \frac{1}{2}$$

Set-based approximation of fuzzy sets

By approximating fuzzy sets by a finite family of sets we can directly exploit well-developed techniques of interval analysis and combine the partial results into a single fuzzy set (result).



9.2 Fuzzy sets and their interfacing with the external world

Fuzzy sets and interfaces

- Fuzzy sets do not exist in real-world (sets do not as well)
- To interact with the world one has to construct interfaces (encoders and decoders)



Fuzzy sets and interfaces

- Need for building interfaces exists in case of sets (interval analysis)
- Here we encounter well-known constructs of analog-to-digital (AD) and digital-to-analog (DA) converters.



Fuzzy sets and interfaces

- Two functional modules:
 - <u>– Encoders</u> The objective is to translate input data into some internal format acceptable for processing at level of fuzzy sets
 - <u>Decoders</u> The objective is to convert the results of processing of fuzzy sets into some format acceptable by the external world (typically in the form of some numeric quantities)
- For encoding and decoding we engage a collection of fuzzy sets information granules

Encoding mechanisms

Given is a collection of fuzzy sets A₁, A₂, ..., A_c; express some numeric input x in **R** in terms of these fuzzy sets

 $x \rightarrow [A_1(x) \ A_2(x) \dots A_c(x)]$

Nonlinear mapping from R to c-dimensional unit hypercube

Decoding mechanisms

- Decoding completed on a basis of a single fuzzy set)
- Decoding realized on a basis of a certain finite family of fuzzy sets and levels of their activation

Decoding process: a single fuzzy set

Single fuzzy set $B \rightarrow$ develop a single numeric representative

$$\hat{x} = \frac{\tilde{x}_1 + \tilde{x}_2 + \dots + \tilde{x}_p}{p}$$
$$\int_{-\infty}^{\hat{x}} B(x) dx = \int_{\hat{x}}^{\infty} B(x) dx$$

Mean of maxima

Centre of Area

$$\hat{x} = \frac{\int B(x) x dx}{\int B(x) dx}$$
X

Centre of gravity

Single fuzzy set decoding: centre of gravity

Solution to the following optimization problem

$$\min_{\hat{x}} V = \int_{\mathbf{X}} B(x) [x - \hat{x}]^2 dx$$

 $\frac{\partial V}{\partial \hat{x}} = 0$

$$2\int_{\mathbf{X}} B(x)[x-\hat{x}]dx = 0$$

Single fuzzy set decoding: augmented strategies

Augmented centre of gravity

$$\int B(x) x dx$$
$$\hat{x} = \frac{x \in \mathbf{X} : B(x) \ge \beta}{\int B(x) dx}$$
$$x \in \mathbf{X} : B(x) \ge \beta$$

$$\int B^{\gamma}(x) x dx$$
$$\hat{x} = \frac{x \in \mathbf{X} : B(x) \ge \beta}{\int B^{\gamma}(x) dx}$$
$$x \in \mathbf{X} : B(x) \ge \beta$$

Single fuzzy set decoding: general requirements

Requirements implied by :

- monotonicity with respect to changeable membership functions

- graphically motivated requirements (symmetry, translation, scaling...)

- use of logic operations and logic modifiers

9.3 Encoding and decoding as an optimization problem of vector quantization

Fuzzy scalar optimization

Decoding: a collection of fuzzy sets



- One-dimensional case
- Multivariable case

Decoding: one-dimensional (scalar) case

Codeboook – a finite family of fuzzy sets $\{A_1, A_2, ..., A_c\}$



Proposition

Assume:

a) $\{A_i\}$ i = 1, ..., c forms a partition

$$\sum_{i=1}^{c} A_i(x) = 1, \quad \forall x \in \mathbf{X}, \quad \exists i \mid A_i(x) > 0$$

b)
$$A_i > 0, A_{i+1} > 0$$
 and $A_k = 0 \quad \forall k \neq i, i+1$

c) decoding is a weighted sum of activation levels and prototypes v_i

$$\hat{x} = \sum_{i=1}^{c} A_i(x) v_i$$

$$\mathbf{v}_{i}(x) = \begin{cases} \frac{x - v_{i-1}}{v_{i} - v_{i-1}} & \text{if } x \in [v_{i-1}, v_{i}] \\ \frac{x - v_{i+1}}{v_{i} - v_{i+1}} & \text{if } x \in [v_{i-1}, v_{i+1}] \end{cases}$$

1

A

Forming mechanisms of fuzzy quantization



use of sets – Vector Quantization (VQ)

use of fuzzy sets – Fuzzy Vector Quantization (FVQ)

Fuzzy vector quantization

- Codebook formed through fuzzy clustering (FCM) producing a finite collection of prototypes v₁, v₂, ..., v_c
- Given any new input x we realize its encoding and decoding
- Recall
 - encoding: representation of x in terms of the prototypes

 decoding: development of external representation of the result of processing realized at the level of information granules

Coding and decoding with fuzzy codebooks

Encoding: optimization problem

$$\sum_{i=1}^{c} u_i^m / |\mathbf{x} - \mathbf{v}_i|/^2$$

Minimize w.r.t.
$$u_i$$
 subject to

$$u_i(\mathbf{x}) \in [0,1], \quad \sum_{i=1}^{c} u_i(\mathbf{x}) = 1$$

$$u_i(\mathbf{x}) = \frac{1}{\sum \left(\frac{//\mathbf{x} - \mathbf{v}_i//}{//\mathbf{x} - \mathbf{v}_j//}\right)^{\frac{2}{m-1}}}$$

Decoding: optimization problem

Reconstruct original mutidimensional input x

$$Q_2(\hat{\mathbf{x}}) = \sum_{i=1}^{c} u_i^m \| \hat{\mathbf{x}} - \mathbf{v}_i \|^2$$

minimize

$$\hat{x} = \frac{\sum_{i=1}^{C} u_i^m \mathbf{v}_i}{\sum_{i=1}^{C} u_i^m}$$

Fuzzy vector quantization: decoding error



m = 1.2



m = 2.0



m = 3.5

9.4 Decoding of a fuzzy set through a family of fuzzy sets

Fuzzy encoding and decoding with possibility and necessity measures

- Consider a family of fuzzy sets A₁, A₂, ..., A_c
- Input datum X either a fuzzy set or a numeric quantity

$$Poss(A_i, X) = \sup_{x \in \mathbf{X}} [X(x) t A_i(x)]$$

Possibility

Necessity

$$\operatorname{Nec}(A_i, X) = \inf_{x \in \mathbf{X}} [X(x) \, s \, (1 - A_i(x))]$$

Possibility and necessity







Necessity

Possibility and necessity encoding: example

 $X = [0.0 \ 0.2 \ 0.8 \ 1.0 \ 0.9 \ 0.5 \ 0.1 \ 0.0]$ $A_i = [0.6 \ 0.5 \ 0.4 \ 0.5 \ 0.6 \ 0.9 \ 1.0 \ 1.0]$ $Poss(A_i, X) = max(0.0, 0.5, 0.4, 0.5, 0.6, 0.5, 0.1, 0.0) = 0.6$ $Nec(A_i, X) = min(0.4, 0.5, 0.8, 1.0, 0.9, 0.5, 0.1, 0.0) = 0.0$

Encoding and decoding: an overview



Design of the decoder of fuzzy data

 Given the nature of encoding (possibility and necessity measures), the decoding is regarded as a certain "inverse" problem in terms of fuzzy relational equations:

– Possibility measure: sup-t composition

- Necessity measure: inf-s composition

Decoding –possibility measure

Possibility measure: sup-t composition

$$\hat{X}(x) = A(x)\varphi\lambda = \begin{cases} 1 & \text{if } A(x) \le \lambda \\ \lambda & \text{otherwise} \end{cases}$$

$$\hat{X}(x) = A(x) \to \lambda = \sup\{a \in [0,1]/a \, t \, A(x) \le \lambda\}$$

$$\hat{X} = \bigcap_{i=1}^{c} \hat{X}_i$$

Decoding –necessity measure

Necessity measure: inf-s composition

$$\widetilde{X}(x) = (1 - A (x))\varepsilon \mu = \begin{cases} \mu, & \text{if } 1 - A (x) < \mu \\ 0, & \text{otherwise} \end{cases}$$

$$\widetilde{X}(x) = (1 - A_i(x))\varepsilon\mu = \inf\{a \in [0,1] \mid as (1 - A(x)) \ge \mu\}$$

$$\widetilde{X} = \bigcup_{i=1}^{c} \widetilde{X}_i$$

$$\tilde{X} \subseteq X \subseteq \hat{X}$$

Decoding: example

Possibility measure







Decoding: example

Necessity measure







Decoding example

Bounds of possibility and necessity measure



Taxonomy of data in structure description with shadowed sets

- Core structure
- Shadowed data structure
- Uncertain data structure

Core data structure

- patterns that belong to a core of at least one shadowed sets

- core data structure = { $x \mid \exists i \ x \in Core(A_i)$ }

Shadowed data structure

- patterns that do not belong to a core of any shadowed set
- core fall within the shadow of one ofr more shadowed sets
- shadowed data structure = { $x \mid \exists i \ x \in \text{Shadow}(A_i) \text{ and } \forall x \notin \text{Core } (A_i)$ }

Uncertain data structure

- patterns that left out from all shadows

- uncertain data structure = { $x \mid \exists i \ x \notin \text{Shadow}(A_i)$ and $\forall x \notin \text{Core}(A_i)$ }

Three-valued characterization of data structure with shadowed sets



Three-valued characterization of data structure: Example





Core

Three-valued characterization of data structure: example









Shadow